

# ALLEN-BRADLEY MVI SETUP 11/11/02



PRELIMINARY

## 1.0 OVERVIEW

**1.1** This motion control system integrates a SLC500 PLC, an MVI46ADM module mounted on the back plane of the PLC, and one to sixteen Servo Sensors™. PLC ladder logic uses predetermined memory locations and a command structure for motion control to the Servo Sensor™. The communications network from the MVI module to the Servo Sensors™ utilizes a two wire RS-485 multi-drop configuration. Refer to MVI500CONNECT.DWG sheet 1 of 5.

### 1.2 Features

- Provides interfacing to S-series MTS® Servo Sensors™.
- One to sixteen Servo Sensors™ controlled from one MVI module.
- Two RS485 ports-each controlling eight ServoSensors™ each.
- One RS232 Com port used by PC to interface Servo Sensor™ setup software if required.
- Hyper-terminal mode can be used to determine status within MVI.
- Translator program is loaded in MVI from front of module using RS232 Com port.
- Communication format is ASCII code.
- Easy machine motion control programming.
- N: memory locations used for loading commands, targets, velocities, and reading status.

For Servo Sensor™ specifications, refer to MTS®.

### 1.3 Communications Port Particulars of the MVI46ADM interface

#### Port 1

- Port 1 used to communicate with a Personnel Computer
- Port 1 baud-rate is 19.2kb.
- Translator Software loaded through this port.
- Used to interface a Personal Computer.
- Servo Sensor™ setup software is operated through this port.
- Hyper-terminal link is run through this port.

#### Port 2

- Port 2 used to communicate to the Servo Sensor™ network.
- Port 2 baud-rate fixed at 115.2 KB.
- Port 2 network will communicate with 1 to 8 Servo Sensors™
- Communication is RS485.
- ASCII code is the protocol used.

#### Port 3

- Port 3 used to communicate to the Servo Sensor™ network.
- Port 3 baud-rate fixed at 115.2 KB.
- Port 3 network will communicate with 1 to 8 Servo Sensors™
- Communication is RS485.
- ASCII code is the protocol used.

### 1.4 MVI-ADM/PLC timing

- Approximately 12msec update time between backplane and MVI.
- Servo Sensor™ update time on Com port 2 & 3 is ~3.5msec per probe.

*This document assumes that the user has computer-keyboarding skills and knowledge of personal computers. If not, operation by unqualified personnel can cause degraded results, non- operation, failures, and possible down time.*

## 2.0 CABLING HOOKUP TO MVI46 MODULE

### 2.1 Items required

- RJ-45 to 9 pin connector cables. (Supplied with MVI module).
- D-9 to terminal breakout adapter. (Supplied with MVI module).
- Refer to PTJ drawing MVI500CONNECT.DWG sheet 2.
- Three position terminal strip or equivalent.
- S-Series Servo Sensor™ controller
- Power/Communications cable with connector for Servo Sensor™ or pigtail for use in multi-drop systems.
- +24VDC Power Supply capable of supplying enough current for the system.
- Small screwdriver

### 2.2 Connection Procedure of Servo Sensor™ to MVI46

- Connect supplied communications cable to P2 or P3
- Plug 9-pin connector into terminal breakout adapter.
- Install power/communications cable as follows:
  - Hook white wire (part of shielded pair) to 1 of the terminal breakout adapter.
  - Black wire (part of shielded pair) to 8.
  - Install jumper from negative 24 VDC Power Supply to 5.
- Ensure good connections. These wires are small and might not make good initial contact.
- Refer to MVI500CONNECT.DWG for terminals of other wires in the power/communications cable.

## 3.0 FRONT PANEL DESCRIPTION

- P1 LED will flash if communications are active with PC.
- P2 and P3 LEDs will flash if communications are active between MVI and Servo Sensors™.
- BP LED will flash 200 Msec on and 200 Msec off. This indicated the MVI module is working

## 4.0 APPLYING POWER TO THE PLC AND SERVO SENSOR™

After connecting, installing, and configuring the MVI46 and the Servo Sensor™, please follows the procedure stated below.

**“CAUTION: Check all power for correct levels. +24vdc should be 24 +/- .05%.”**

### 4.1 Procedure

- Connect the Power/Com cable to the Servo Sensor™
- Apply 24vdc power to the system.
- The expected responses are as follows:
  - BP lamp is flashing at a fast rate.
  - Depending on the communications port used either P2 (port2) and/or P3 (port3) will be flashing.

## 5.0 PLC PROGRAMMING WITH THE MVI46

*This document assumes that the user has computer-keyboarding skills, has PLC programming skills, knowledge of personal computers, and PLC's. If not, integration by unqualified personnel can cause degraded results, non- operation, failures, and possible down time.*

### 5.1 Items required.

- Notebook or equivalent PC
- RSLOGIX 500 software.
- RSLINX software
- Optional: AB displays
- Optional: Automation Direct EZ Touch display
- Optional: EZ Touch Editor Software
- Optional: Servo Sensor™ setup software

5.2 An Excel spreadsheet Appendix C contains the memory structure, the command structure, and notes of how the commands are used.

- Program MVI46-SS1 transfers 33 words of status and setup data from MVI46 to N30:0.
- One hundred (100) words of received data from MVI46 are stored in N31:0.
- One hundred (100) words of data are sent to MVI46 from N32:0
- First Word of data received by PLC From MVI46 must be returned in first data word sent back to MVI46 (N31:0 to N32:0).

5.3 Use advanced configuration I/O to setup MVI using 500 software. Entries shown as follows:

Figure 5.1

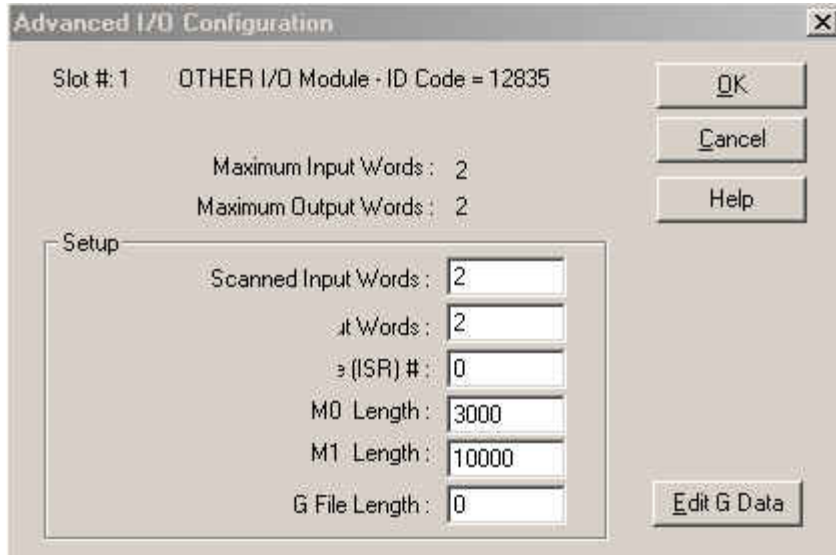


Figure 5.2

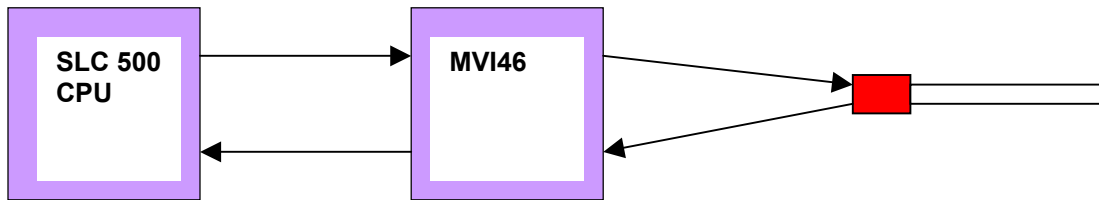
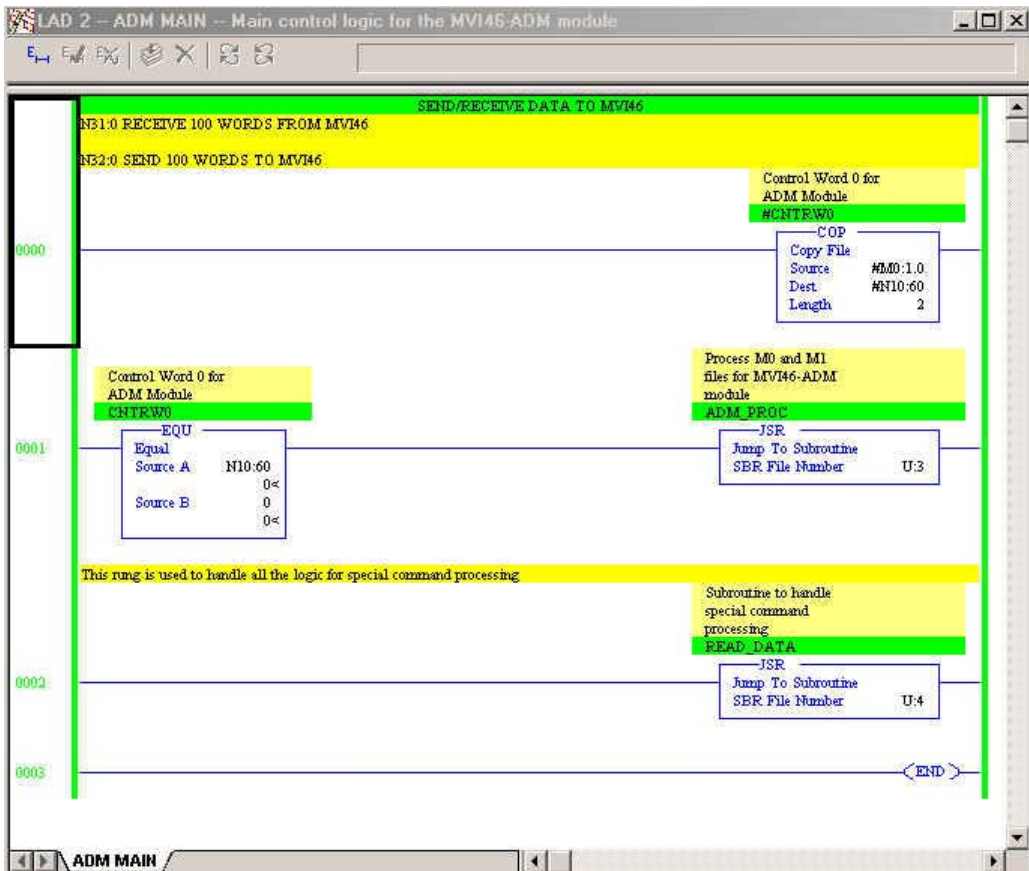
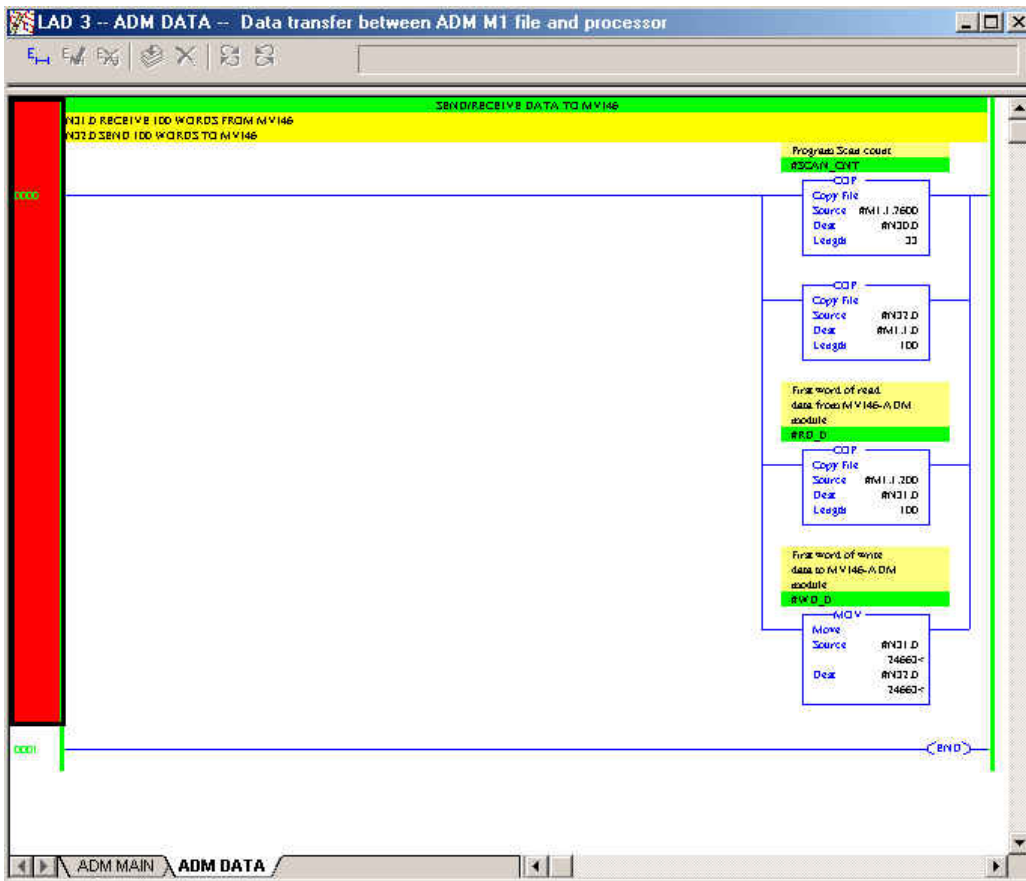


Figure 5-2 ADM Main program



The above picture shows the rungs used in the main body of a program. Note the jump instructions to sub routines.

Figure 5-3 ADM DATA Screen



The above picture shows a subroutine ladder that the PLC needs with the MVI module. Change the Integer (N:XX) locations when needed.

Figure 5-4 ADM CMDS Ladder

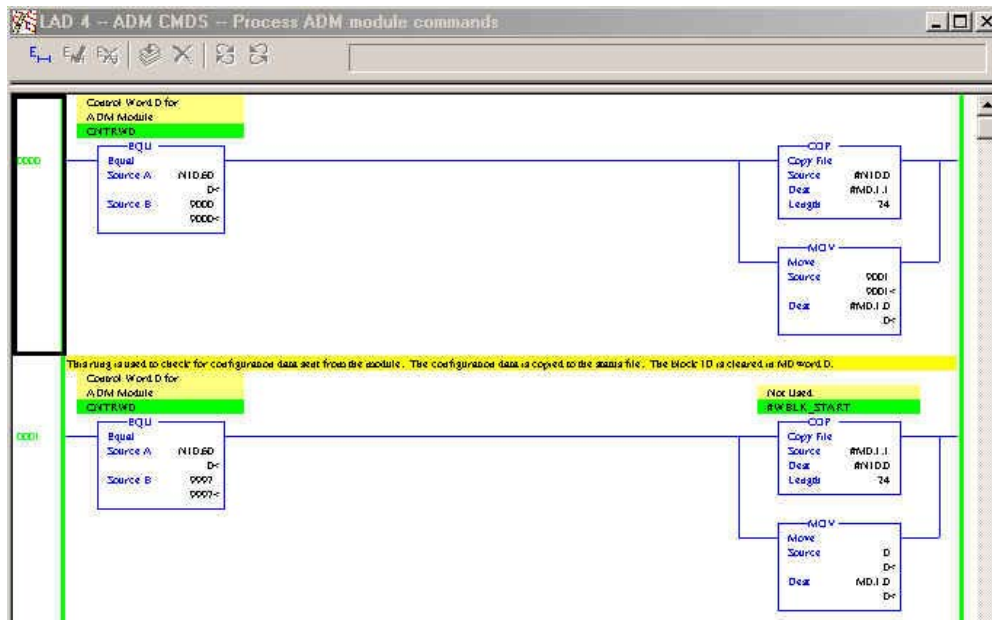
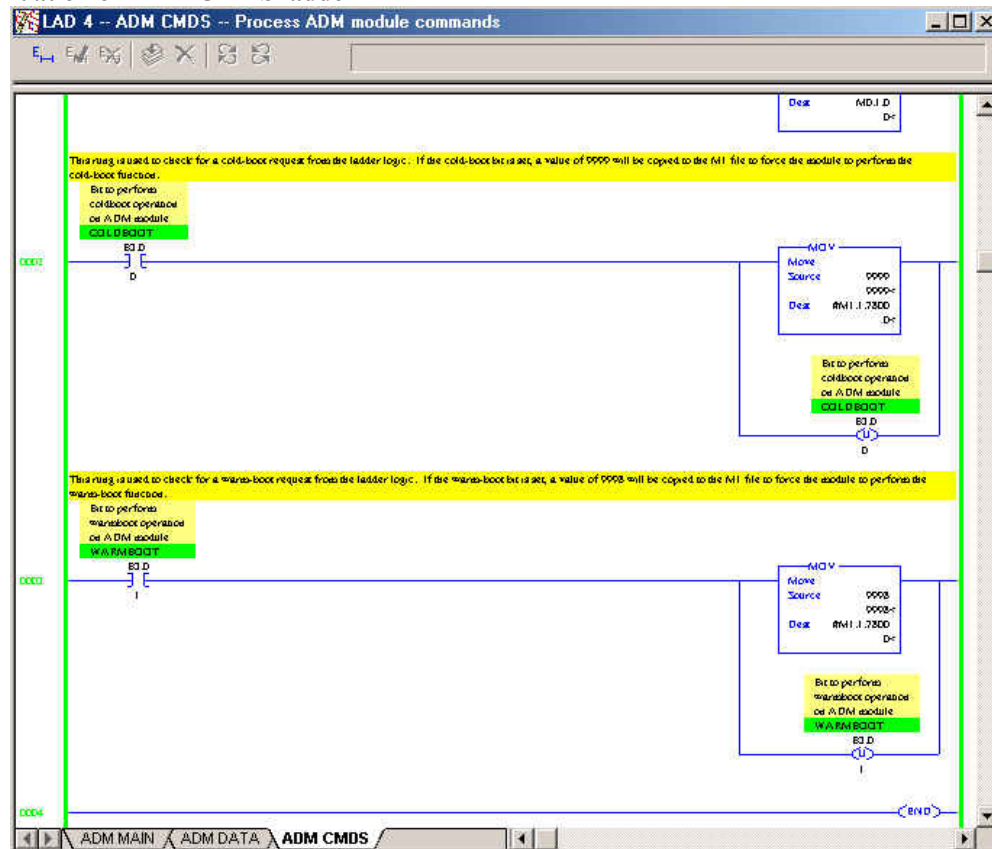


Figure 5-5 Continuation of ADM CMDS ladder



## 6.0 MVI46/ADM CONFIGURATION/SETUP

The PTJ software package incorporates all required files including the Servo Sensor™ interface program.

### 6.1 Items required.

1. SLC500 PLC platform with available slot
2. MVI46ADM module from ProSoft Technology, Inc.
3. PTJ Translator program (abslc-ss1.IMA)
4. MVI Tools Software. (Contains manual, etc.)

### 6.2 Program Loading Procedure 1 (Recommended)

1. The program can also be loaded to the MVI as a ROM Disk Image.
2. Refer to Prosoft Technology Manual 5.3.
3. All files required for the MVI are contained in the program named abslc-ss1.IMA This is a WINIMAGE file.
4. Remove power from PLC.
5. Move jumper JP3 from Run/Clear to Setup.
6. Connect PC to Port 1 using the supplied null modem cable and RJ45/9pin cable.
7. Start MVI Flash Update Utility program. Program is supplied with ADM package.
8. Select Com Port.
9. Power up module.
10. Choose file **\*\*\*.IMA** (abslc-ss1.IMA)
11. Download.
12. Remove Power.
13. Move jumper JP3 to engage only the Run/Clear pin.
14. Power up module.
15. MVI is ready for operation.
16. Move JP1 and JP2 to RS485.

## 7.0 MVI46ADM PROGRAMMING NOTES

The following discussions will explain some of the basic criteria that the PLC programmer should consider when writing the program. Since every programmer has their own approach, the explanations are only for idea purposes. Appendix C lists the command structure.

### PLC Leading Particulars

Consider the stroke of the Servo Sensors™ at all times when sending targeting information and viewing position information. All commands to/from the MVI are listed in decimal format.

Hex/Octal equivalents can be used.

The target value can not exceed the programmed stroke of the Servo Sensor™.

Table 7-0 Programs

Device	Program	Description
ProSoft MVI46ADM	Abslc-ss1.IMA	Servo Sensor™/MVI translator
SLC500	MVI46-SS.RSS	Basic Sample

## 8.0 MVI AND THE HYPER-TERMINAL (NOT USED PRESENTLY)

Displays showing the MVI program name, buffer status, and active Servo Sensors™ are viewed with this method.

### 8.1 Item required.

- RJ45/9 pin cable (supplied with MVI module)
- Null modem cable (supplied with MVI module)

### 8.2 Procedure

- Connect cable between P1 of the MVI and the Com port connector on the PLC.
- Apply Power.
- The BP lamp will flash if MVI is working.
- P2 and/or P3 will flash indicating the PC COM port is active.
- Create a hyper-terminal link in the PC using 19.2kb, 8-n-1.
- Change the Number of Servos memory location to 902 if com port two is used or 903 if com port 3 is used.
- The following commands will display information as described.
  - Lower case “n” displays Coprocessor program name, date, and active Servo Sensor™ names and serial numbers on the network. Refer to Figure 1.
  - Lower case “s” continuously displays all servo positions and status. Refer to Figure 2.
  - Lower case “p” continuously displays in buffer from plc. Refer to Figure 3.

**CAUTION: MAKE SURE THAT THE SYSTEM IS NOT LEFT IN ONE OF THE CONTINUOUS MODES. THE SYSTEM WILL SLOW DOWN BECAUSE OF THE 19.2KB TRANSMISSION.**

- Strike any other key to leave these modes.

Figure 8-1 “n” display

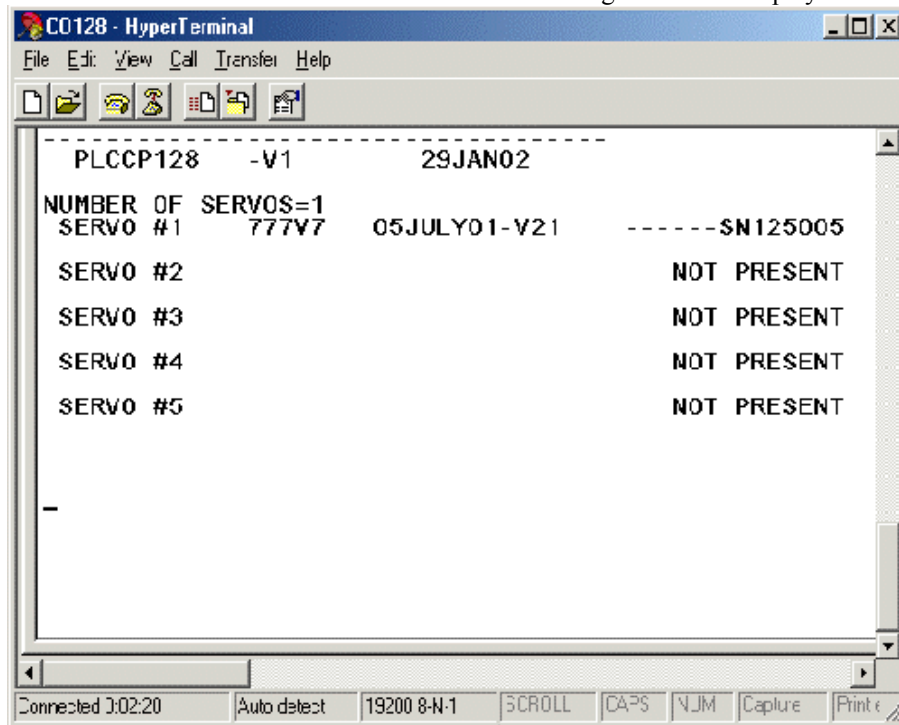
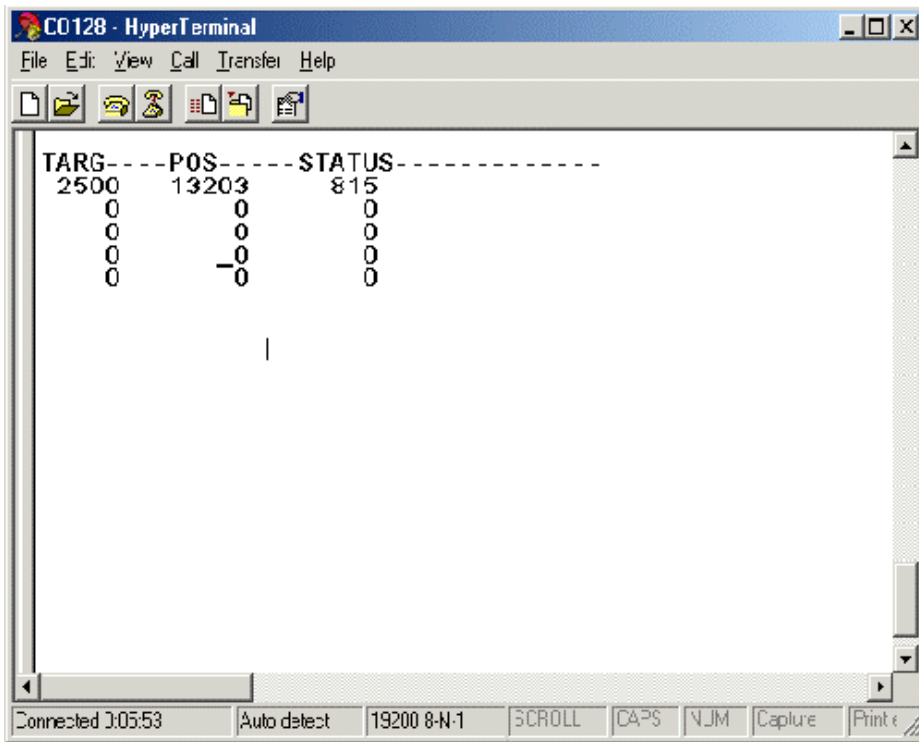


Figure 1 is a copy of the actual screen when using the hyper terminal feature. As noted previously, the program name and date is shown on the first line. The “number of servos” indicates the number of Servo Sensors™ on the network. Below this header the program name, date, and serial number is shown.

Figure 8-2 “s” display



The screen to the left illustrates a typical display when one Servo Sensor™ is called. The target position represents an operator position selection. The Position column reflects the actual position of the magnet on the Servo Sensor™ wand. The Status number equates to a 16-bit word that is sent from the Servo Sensor™ back to the controller. Each bit within the Status word represents a particular function is active.

Figure 8-3 “p” display

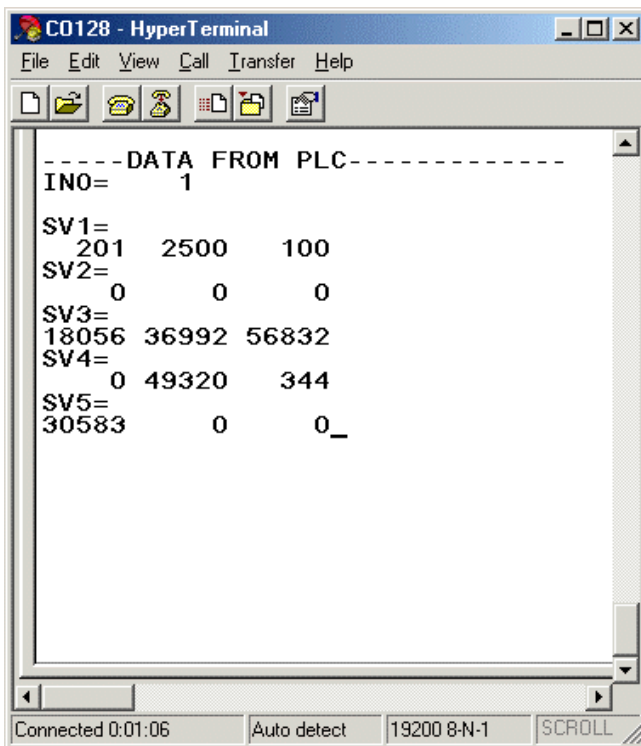
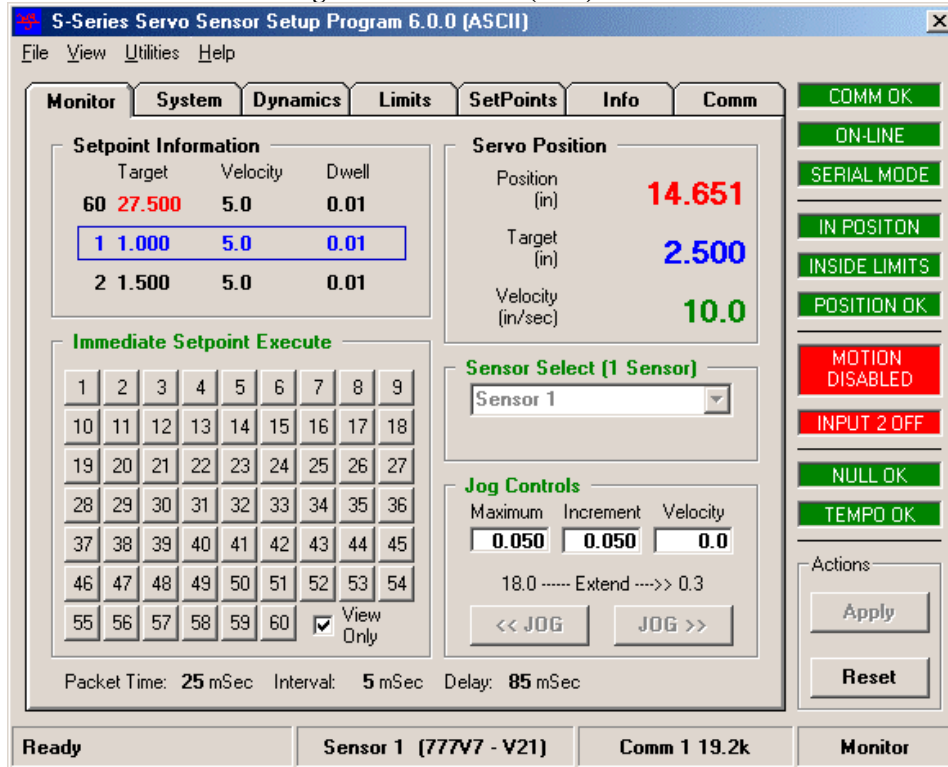


Figure 3 shows the data calls from the PLC. IN0=# is the number of Servo Sensors™ that are programmed for the ladder logic program. This is determined in V2000 memory location. SV1 shows the command located in V2001. The next column is the target value located in V2002. The third column represents the velocity value sent to the Servo Sensor™. Its memory location is V2003. All other numbers in the columns are “trash numbers” in memory locations for other Servo Sensors™ that are not used.

## 9.0 USING SERVO SENSOR™ SETUP SOFTWARE

The Servo Sensor™ setup software may be used for programming the Servo Sensors™ via the MVI module. If parameter access is not programmed within the PLC ladder logic, this method is used.

Figure 9-1. Monitor (Run) Screen



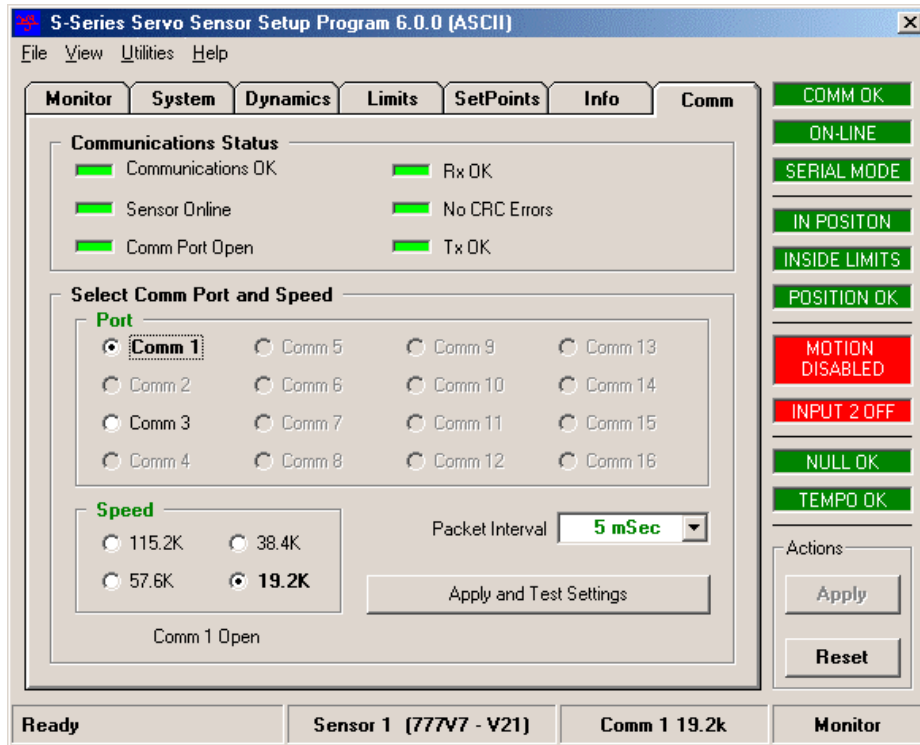
### Items required

- RJ-45 cable with 9 pin D female connector installed on one end. (This assembly comes with the purchase of the MVI Module.)
- Null Modem cable (Supplied with MVI module)

### Procedure

- RSLOGIX 500 and RSLINX software must be off. When the software is in use, the Setup software will have a conflict with the communications port.
- Connect cable between P1 CFG jack of the MVI and the Serial port of the PLC.
- Load N:32/3 Word 3 with 902 decimal for com port 2 or 903 decimal for com port 3. This could be a switched input.
  - This switches the MVI active port to Port 1 CFG (RS-232).
- Select the Servo Sensor™ setup icon.
  - The set up program will start.
- The next 3 steps may not be required if the Servo Sensor™ setup software is already configured to communicate at 19.2kb.
- After the splash screen is finished, select the Com tab.

Figure 9-2. Communication Tab



- Change the baud rate to 19.2kb and verify the pc com-port that is used.
- Select the Apply and Test Settings bar to restart a new search for the Servo Sensors™ on the network. The program will acknowledge the units on the network and the program can now be used to program/setup the selected Servo Sensor™/s.
- Follow the Servo Sensor™ manual or the help function of the software.

## APPENDIX A: SERVO SENSOR CONTROLLER REPLACEMENT

Recommended SS removal and installation procedures are very important to minimize downtime and prevent further system damage. This chapter covers the steps for replacement of SS used with hydraulic cylinders.

Some cylinders have probe guards attached to the end of the cylinder to prevent SS damage. Other cylinders have the probe cap and cable completely enclosed. Use the appropriate wrenches necessary to remove and reinstall the guards.

The SS has a connector ensemble located at the head electronics, which gives the user quick- disconnect ability. The SS utilizes the Temposonics III platform, so the removal and installation is much easier.

### REMOVAL OF SS

#### WARNING

**OBSERVE ALL LOCAL LOCKOUT AND SAFETY PROCEDURES!**

- Turn off motion system power and control power to hydraulics. **Lock Out!**
- Insure area around the SS is clean and free of dirt, sawdust, and any other foreign material.
- Survey the area in back of the cylinder to make sure there is sufficient room to withdraw the SS without encountering obstructions.
- Remove all protective covers from the back of the probe and cable.
- Disconnect cables from SS and secure away from work area.
- Loosen two hex head screws at head electronics.
- Slide the sensing element/electronics assembly out of the high-pressure tube.
- Wipe cables clean of any hydraulic oil that might have come in contact with them. (Hydraulic oil can cause deterioration of cable integrity.)
- Proceed with SS replacement immediately.

### INSTALLATION OF SS

#### WARNING

**OBSERVE ALL LOCAL LOCKOUT AND SAFETY PROCEDURES!**

1. Verify the new SS is compatible with the old SS.
2. Maneuver the SS element tip into the hole of the high-pressure tube.
3. Tighten the probe securely with the two hex head screws used during removal.
4. Clean and reconnect the cables to the probe.
5. Reinstall guard or protective probe and cable cover. (**Note:** this step may be required prior to reconnecting cable.)
6. Power may now be re-applied to the motion system.
7. Verify the SS is working with the motion system electronics.
8. It is possible the SS will need an address change when on a multiple axis system. Consult addressing procedure.
9. Turn on hydraulics power.
10. Proceed with operation of the machine.
11. If problems are still present, consult Troubleshooting chapter of the manual for other possible solutions.

## APPENDIX B

**Paw-Taw-John Services, Inc.**  
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**ALLEN-BRADLEY CONTROL LOGIX MVI**  
**1746-MVI MODULE**  
**SLC500 PLC**  
 4-NOV-02  
 MVI455

PROGRAM no:  
 PLC Desc:  
 PROGRAM Date:  
 PROGRAM Name:

**DATA FROM PLC (16 axis=82 WORDS)**

**ALL COMMANDS ARE SHOWN IN DECIMAL FORMAT**

No.	MEMORY	DESCRIPTION	PORT & ADDRESS						Notes
			Axis 1	Axis 2	Axis 3	Axis 4	Axis 5	Other	
1	N:320 Word 0	Output sequence							
2	N:321 Word 1	Input acknowledge							
3	N:322 Word 2	Number of Servos or Setup Command							
4	N:323 Word 3	Port 2 and Servo address	200						<p>Enter the number of Servo Sensors™ used on the system. If the number of Servos is set = to 902 or 903 then the PLC passes control to PTJ Servo Sensor™ set up software. The Servo Sensor™ software communicates from the computer connected to the Port 1 (RS232 port) at 19200 baud to the Servo Sensors™.</p> <p>Port 2 Servo Sensor™ call code. Example: Port 2 Servo Sensor™ Address 1= 201</p> <p>Port 3 Servo Sensor™ call code. Example: Port 3 Servo Sensor™ Address 1=301</p> <p>Note: Port and Address must be the port the probe is on and address is the new address desired.</p> <p>Most Significant 3 digits of Serial Number must be in Target MSB value.</p> <p>Least Significant 3 digits of Serial Number must be in Target LSB value.</p>
5	N:324 Word 4	Servo Command	300	201	202	203	204	205	
6		101=Jog Fwd		301	302	303	304	305	
7		102=Jog Rev						306-308	
8		200=Write Target						206-208	
9		300=Read Servo Sensor™ Parameter						209-211	
10		400=Write Servo Sensor™ Parameter						212-214	
11		500=Write Address From Serial number						215-217	
12		600=Write Increment to position offset						218-220	
13		800=Write target and velocity. Return Status and Position						221-223	
14		Servo 1 Target MSB or Internal Servo Sensor™ parameter						224-226	
15		Servo 1 Target LSB						227-229	
16		Servo 2 Port and Address						230-232	
17		Servo 2 Command						233-235	
18		Servo 2 Target MSB						236-238	
19		Servo 2 Target LSB						239-241	
20		Servo 2 Velocity						242-244	
21		Servo 3						245-247	
22		Servo 4						248-250	
23		Servo 5						251-253	
24		Servo 6						254-256	
25		Servo 7						257-259	
26		Servo 8						260-262	
27		Servo 9						263-265	
28		Servo 10						266-268	
29		Servo 11						269-271	
30		Servo 12						272-274	
31		Servo 13						275-277	
32		Servo 14						278-280	
33		Servo 15						281-283	

			Axis 1	Axis 2	Axis 3	Axis 4	Axis 5	Other	Notes
26	Word 78-82	Servo 16							
27									
28									
29									
30									
31									
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36									
37									
38									
39									
40									
41									
42									
43									
44									
45									
46									
47									
48									
49	MEMORY	DATA FROM MVI TO PLC							
50	N:31/0 Word 0	Incremented each time							
51	N:31/1 Word 1								
52	N:31/2 Word 2								
53	N:31/3 Word 3								
54	N:31/4 Word 4	Servo 1 Status							
55	N:31/5 Word 5	Servo 1 Position MSB							
56	N:31/6 Word 6	Servo 1 Position LSB							
57	N:31/7 Word 7	Servo 1 Target MSB							
58	N:31/8 Word 8	Servo 1 Target LSB							
59	N:31/9 Word 9	Servo 2 Status							
60	N:31/10 Word 10	Servo 2 Position MSB							
61	N:31/11 Word 11	Servo 2 Position LSB							
62	N:31/12 Word 12	Servo 2 Target MSB							
63	N:31/13 Word 13	Servo 2 Target LSB							
64	N:31/14 Word 14	Servo 3 Status							
65	N:31/15 Word 15	Servo 3 Position MSB							
66	N:31/16 Word 16	Servo 3 Position LSB							
67	N:31/17 Word 17	Servo 3 Target MSB							
68	N:31/18 Word 18	Servo 3 Target LSB							
69	N:31/19 Word 19	Servo 4 Status							
70	N:31/20 Word 20	Servo 4 Position MSB							
71	N:31/21 Word 21	Servo 4 Position LSB							
72	N:31/22 Word 22	Servo 4 Target MSB							
73		Servo 4 Target LSB							
74									
75	Word 23-27	Servo 5							
76	Word 28-32	Servo 6							
77	Word 33-37	Servo 7							
78	Word 38-42	Servo 8							
79	Word 43-47	Servo 9							
80	Word 48-52	Servo 10							
81	Word 53-57	Servo 11							
82	Word 58-62	Servo 12							
83	Word 63-67	Servo 13							
84	Word 68-72	Servo 14							
85	Word 73-77	Servo 15							
86	Word 78-82	Servo 16							
87									
88									
89									
90									
91									
92									

Also parameter MSB. (MSB is whole number value over 32767)  
Also parameter LSB  
Or 0. (MSB is whole number value over 32767  
Or parameter #



